

Seismic Reflection Imaging – from Time to Depth

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The task of reflection seismics

- ▶ explore subsurface with elastic waves
 - ▶ controlled source at known position and source time
 - ▶ many receivers at known positions
 - ▶ perform many experiments to obtain highly redundant data
- ▶ generate image of subsurface

acquired data in time domain



structural image in depth domain

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 - ▶ estimate physical properties of subsurface

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Seismic sources

- ▶ land seismicity
 - ▶ explosives
 - ▶ vibrators
 - ▶ (accelerated) drop weights
- ▶ marine seismicity

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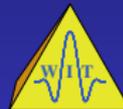
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 - ▶ air guns

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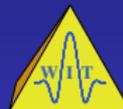
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Seismic receivers

- ▶ land seismics
 - ▶ geophone
 - ▶ measured quantity:
one or more components of particle velocity (or acceleration) vector
- ▶ marine seismics
- ▶ final result: multicoVERAGE data in time domain,
discrete time series for discrete source and receiver
locations

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Seismic receivers

- ▶ land seismics
 - ▶ geophone
 - ▶ measured quantity:
one or more components of particle velocity (or acceleration) vector
- ▶ marine seismics
 - ▶ hydrophones (in streamer)
 - ▶ measured quantity: pressure changes
- ▶ final result: multicoVERAGE data in time domain,
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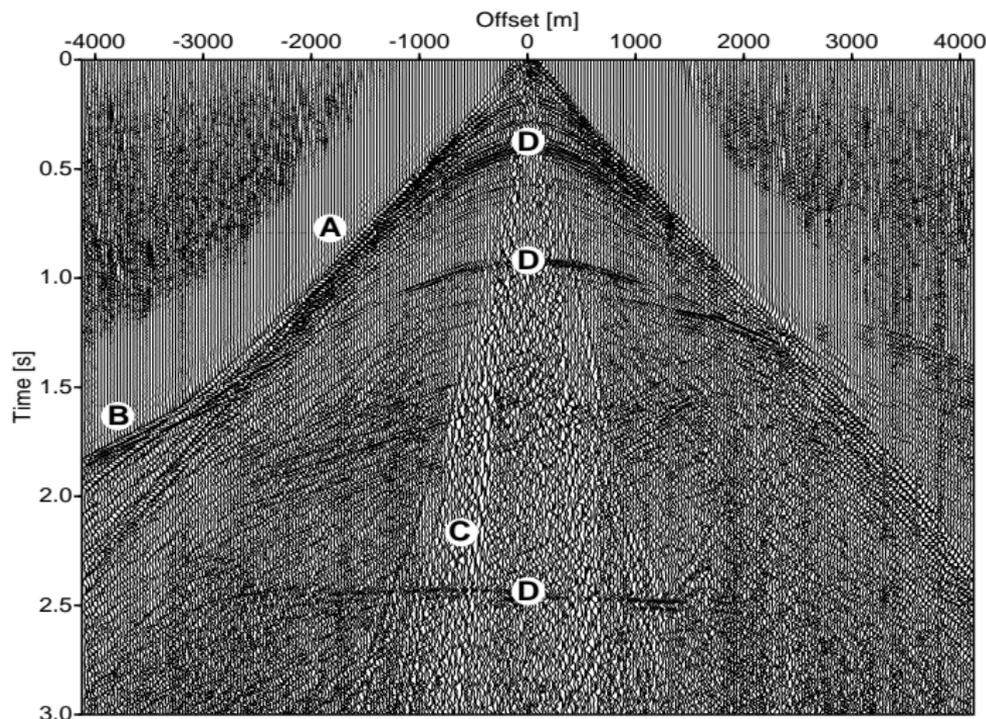
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A field data record

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A: direct wave B: refracted waves
C: ground roll D: reflected waves

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Assumptions

- ▶ assumptions in the following:
 - ▶ isotropic, laterally inhomogeneous model
 - ▶ no a priori information about velocity model
 - ▶ ray theory is applicable
 - ▶ only primary reflection events
- ▶ restrictions for the sake of simplicity:

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 - ▶ the subsurface is 2.5D
 - ▶ 2D acquisition along a straight profile line

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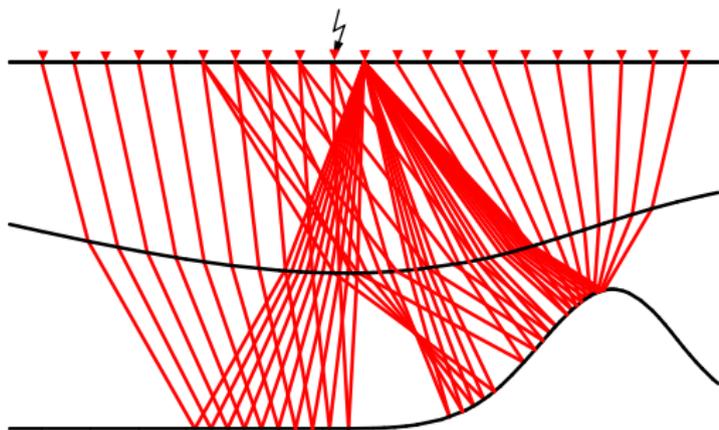
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Data sorting

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▶ common-shot configuration (as acquired)

▶ observations:

- ▶ various points on reflector illuminated
- ▶ rays pass through different parts of overburden

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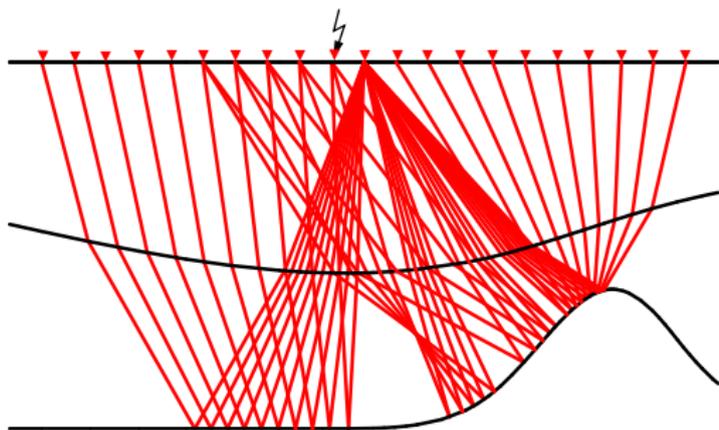
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- ▶ common-shot configuration (as acquired)
- ▶ observations:
 - ▶ various points on reflector illuminated
 - ▶ rays pass through different parts of overburden
 - ↳ no common features
 - ↳ extremely difficult to extract useful information

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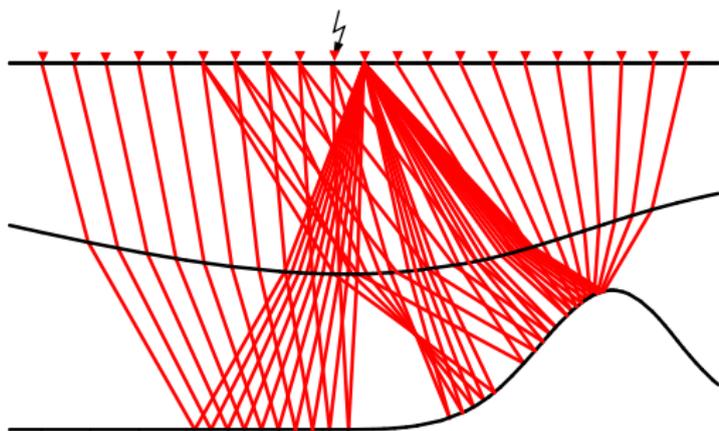
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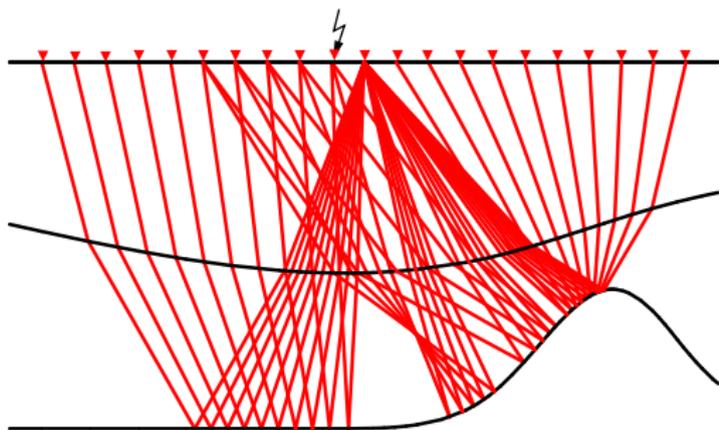
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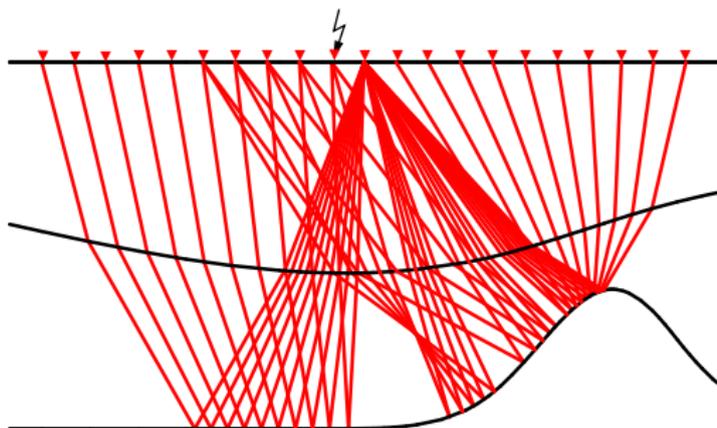
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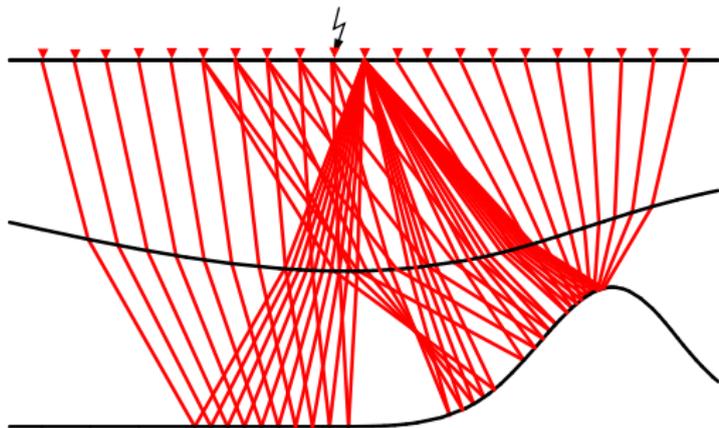
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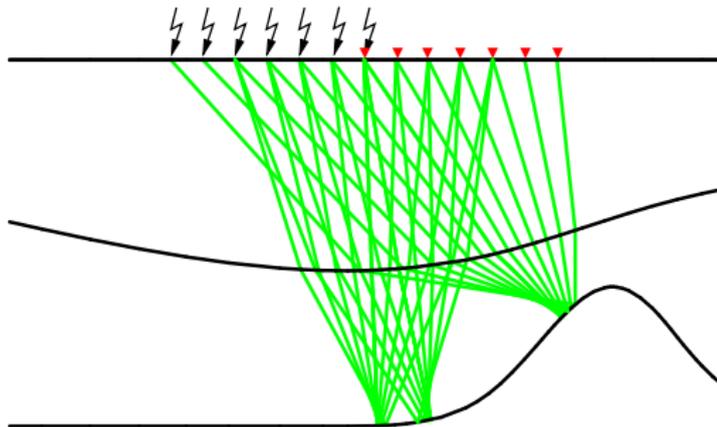
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- ▶ common-midpoint configuration
- ▶ observations:

- ▶ reflection points more or less focused
- ▶ requires dip moveout correction

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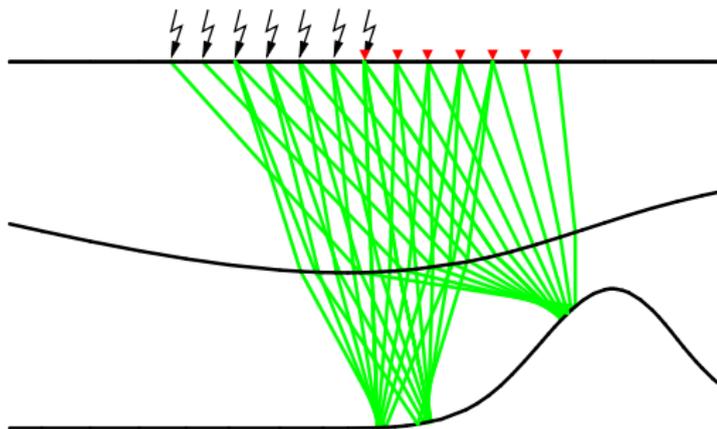
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- ▶ common-midpoint configuration
- ▶ observations:
 - ▶ reflection points more or less focused
 - ↳ requires dip moveout correction
 - ▶ rays pass through different parts of overburden
 - ▶ second-order approximation of traveltimes available
 - ▶ allows stacking velocity analysis (1 parameter)

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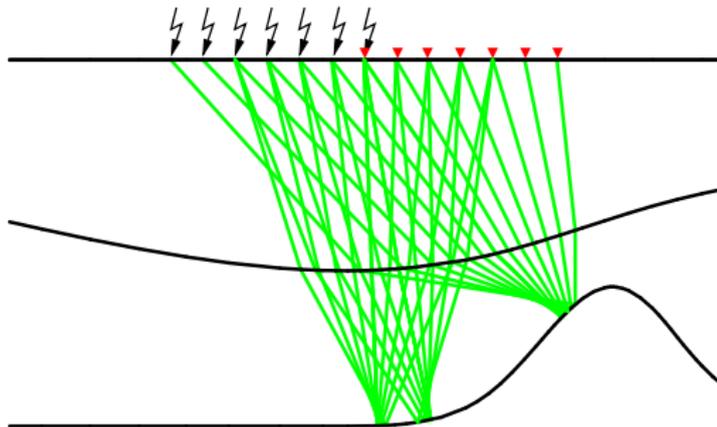
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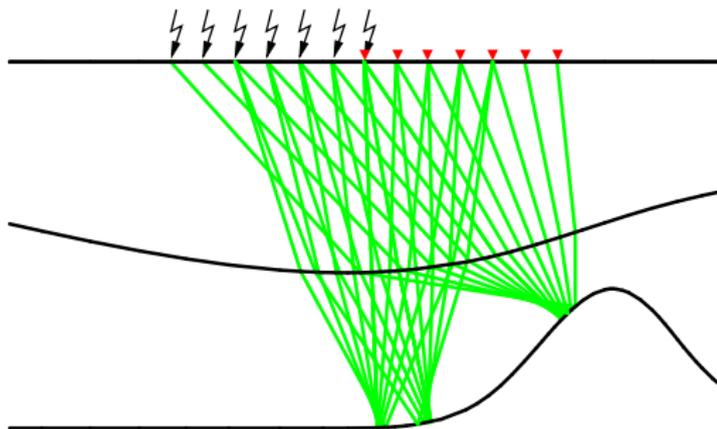
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 - ▶ allows stacking velocity analysis (1 parameter)

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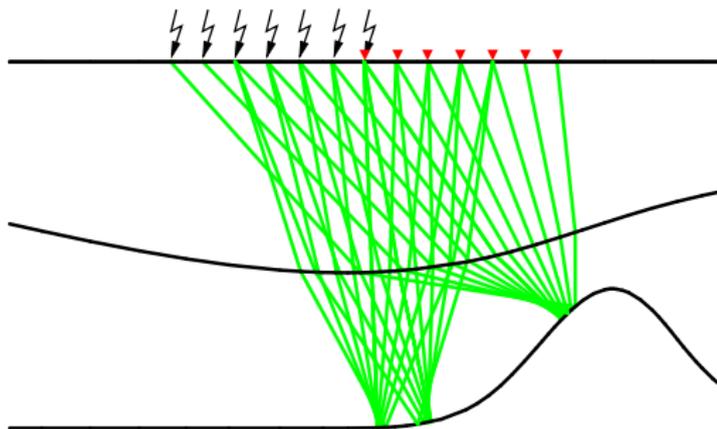
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Data sorting



- ▶ common-midpoint configuration
- ▶ observations:
 - ▶ reflection points more or less focused
 - ➔ **requires dip moveout correction**
 - ▶ rays pass through different parts of overburden
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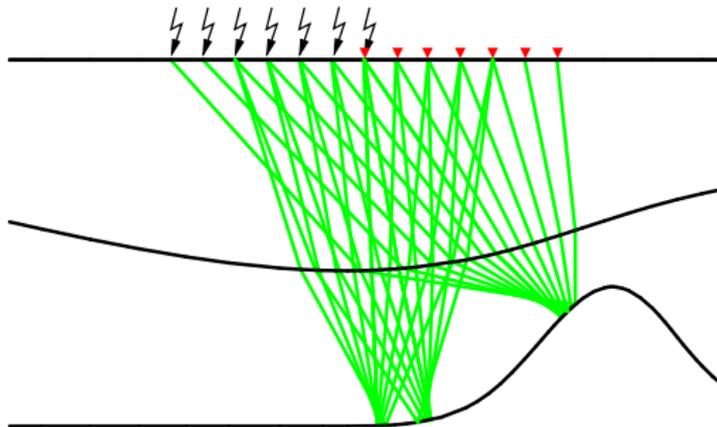
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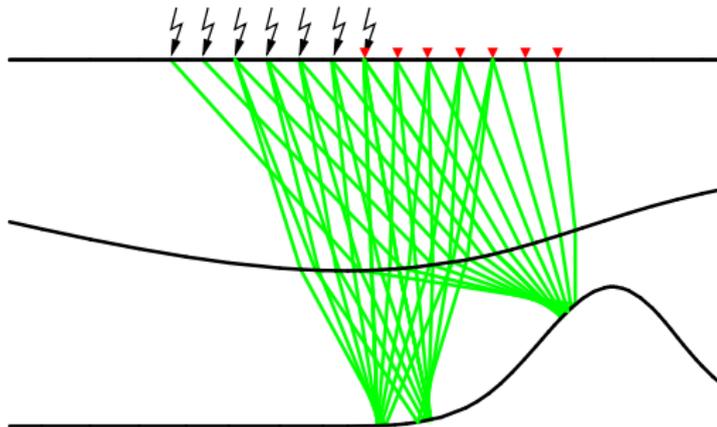
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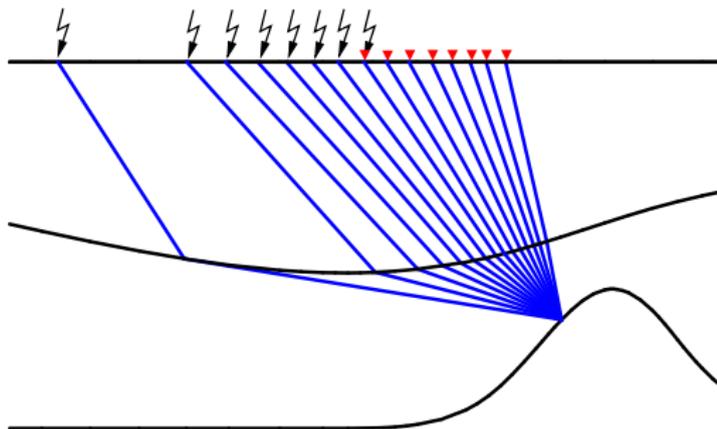
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Data sorting



▶ common-reflection-point (CRP) configuration

▶ observations:

- ▶ focuses in exactly one reflection point
- ▶ rays pass through different parts of overburden

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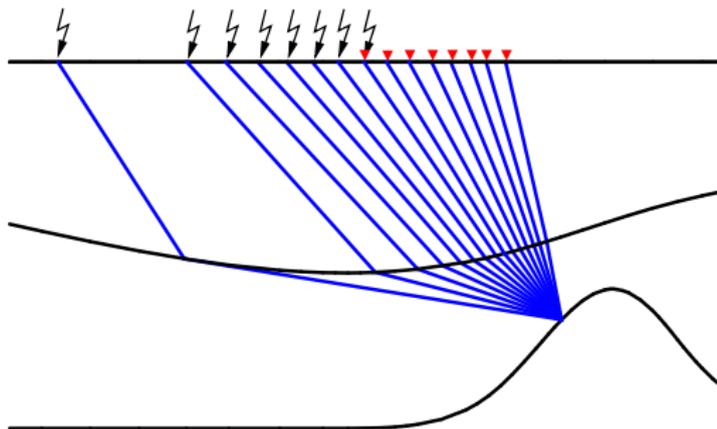
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Data sorting



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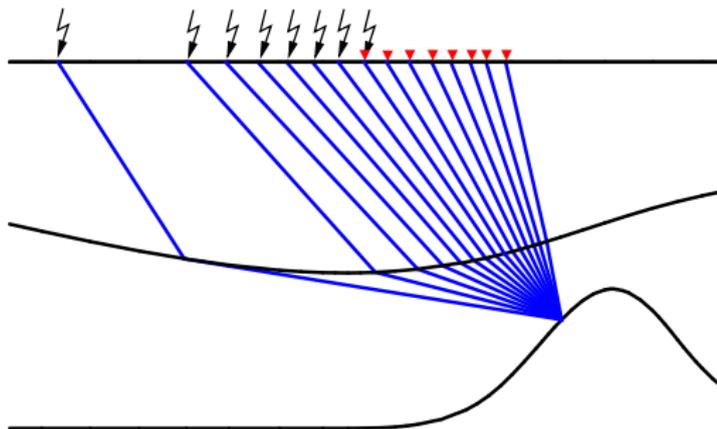
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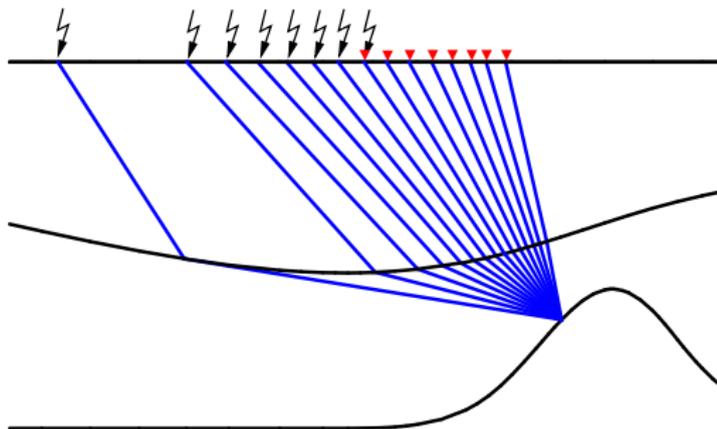
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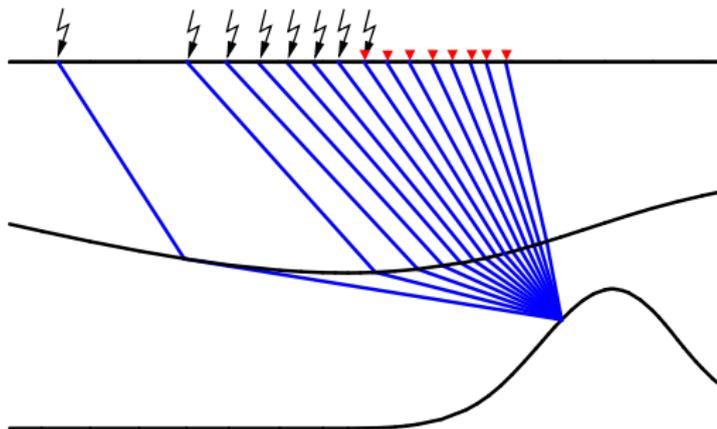
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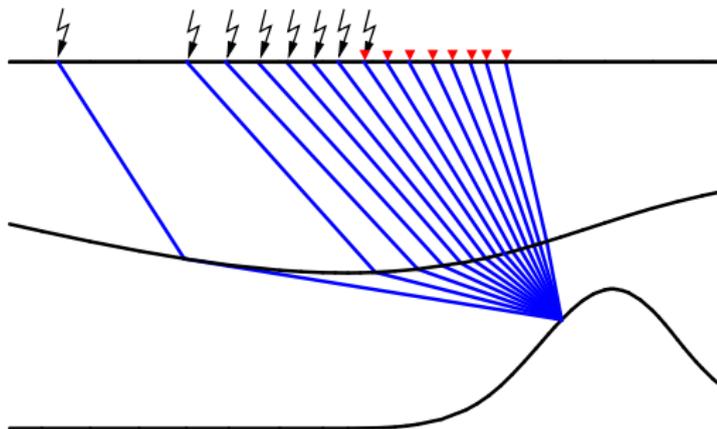
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Data sorting



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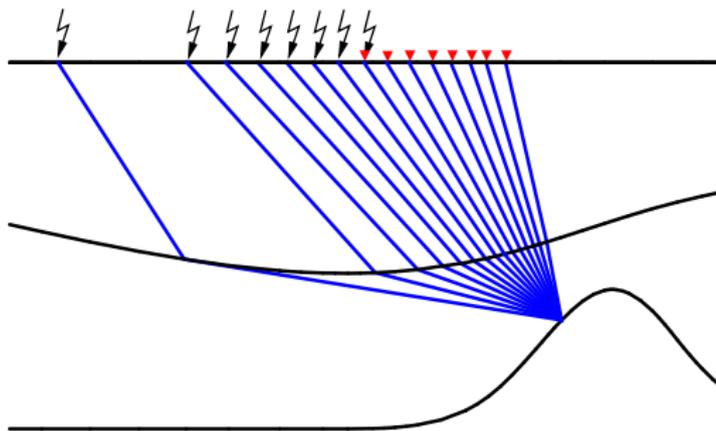
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Stacking

- ▶ traveltimes approximation allows to simulate zero-offset (ZO) sections



- ▶ (generalized) stacking velocity analysis provides information about overburden
 - ↳ basis for velocity model determination

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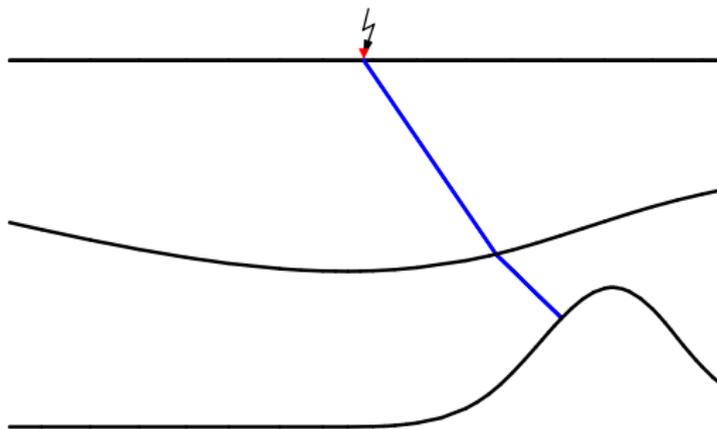
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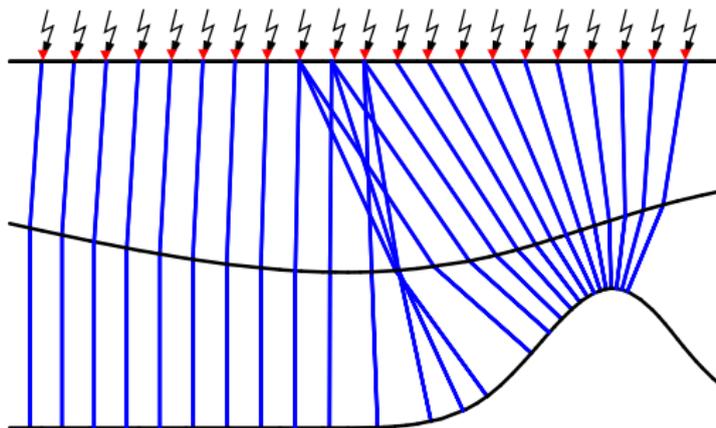
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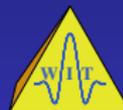
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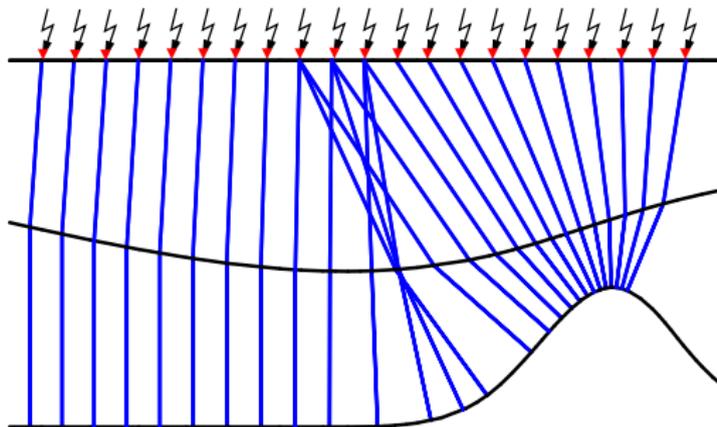
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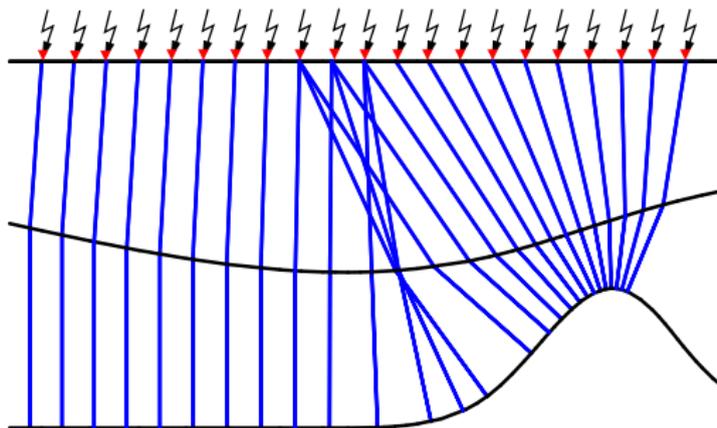
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Common-Reflection-Surface stack

- ▶ (generalized) stacking velocity analysis
 - ▶ search for stacking operator fitting best actual reflection event
 - ▶ based on coherence analysis
- ▶ data-driven stacking with CRP trajectories
- ▶ solution:

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Common-Reflection-Surface stack

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 - ▶ highly ambiguous, hardy application
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 - ▶ i.e., consider neighboring CRPs

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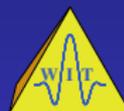
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 - ▶ i. e., consider neighboring CRPs
 - ▶ i. e., consider local curvature of reflector
 - ↳ fitting *spatial operator* to *traveltimes surface*
 - ↳ three stacking parameters

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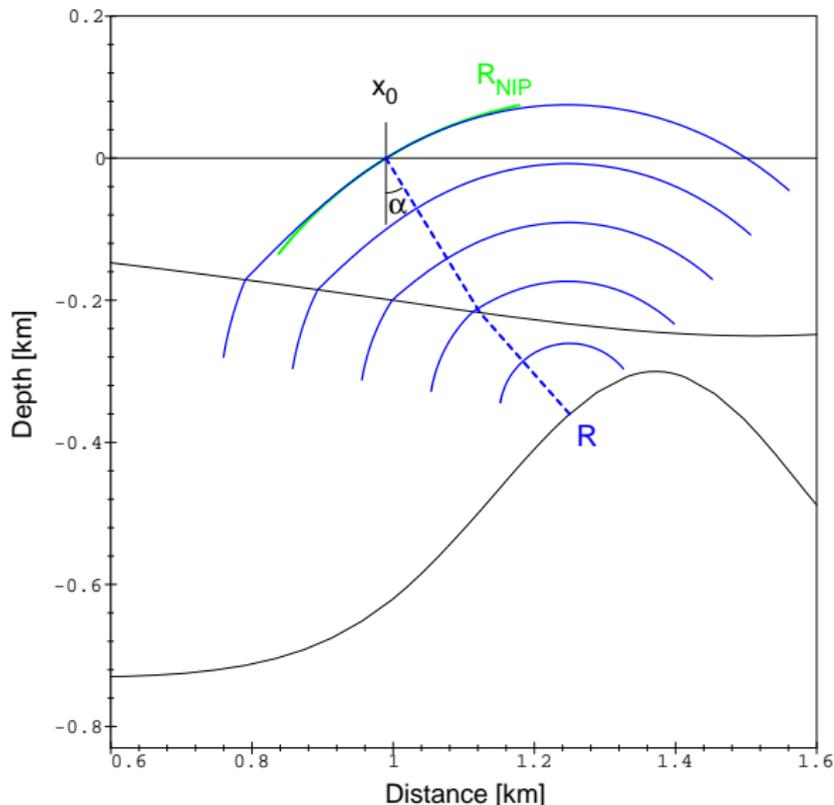
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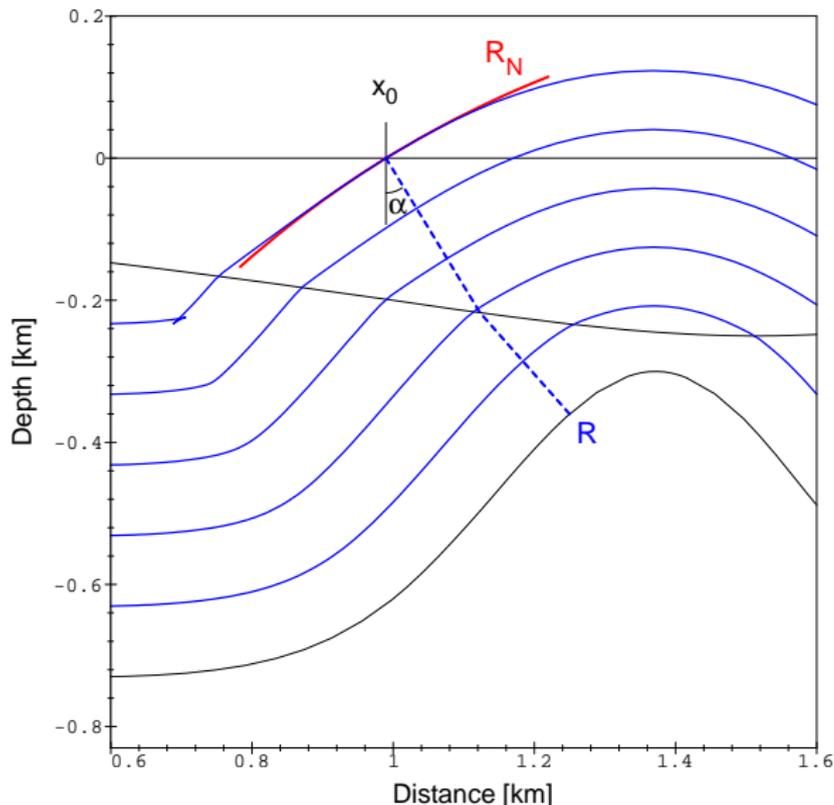
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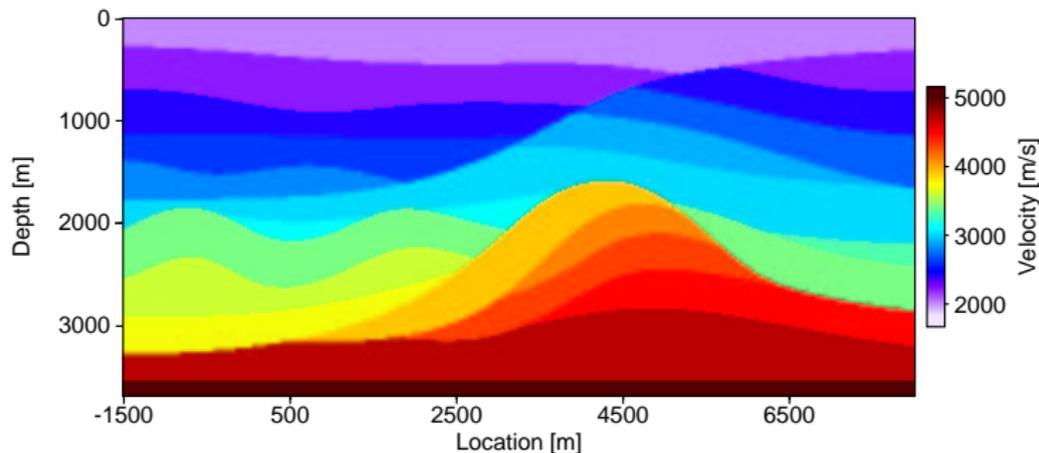
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Velocity model for synthetic data

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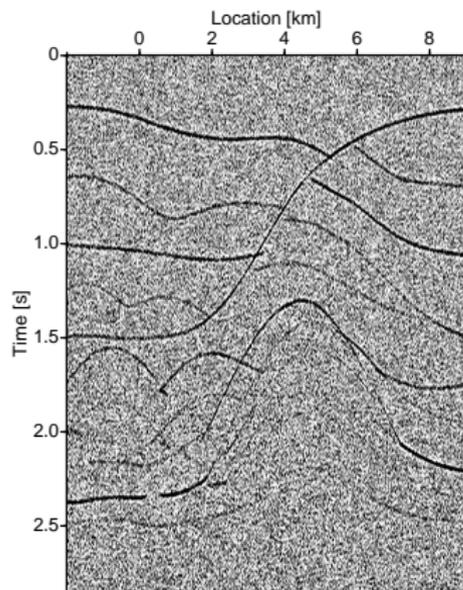
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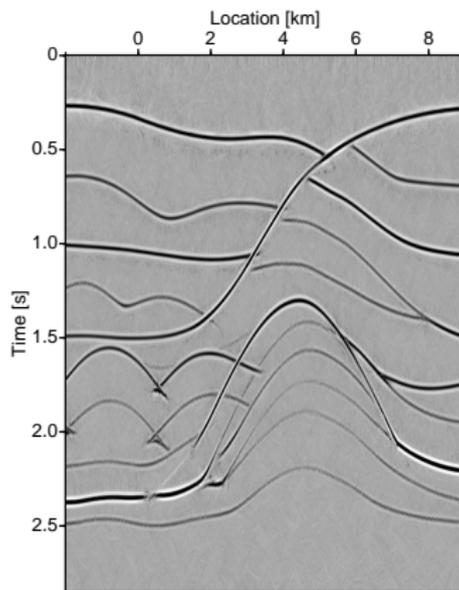
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Near-offset section



CRS stacked section

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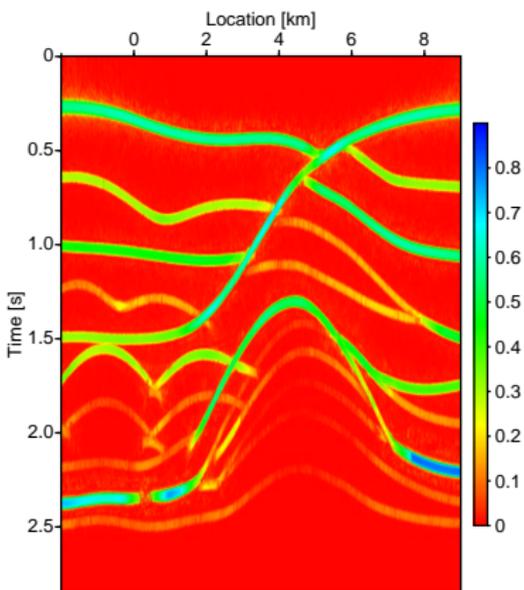
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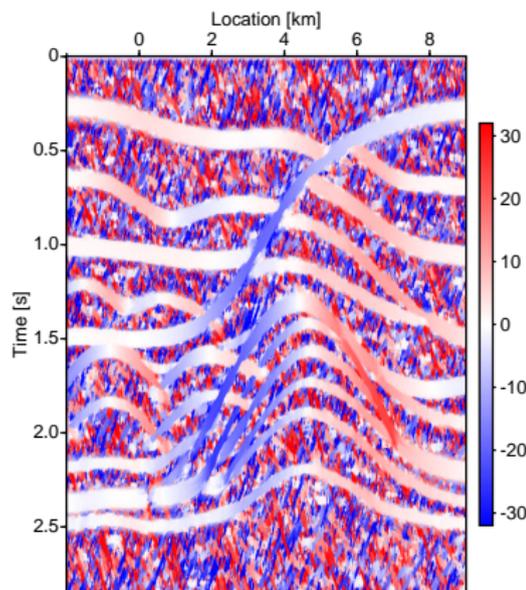
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Coherence section



Emergence angle section [°]

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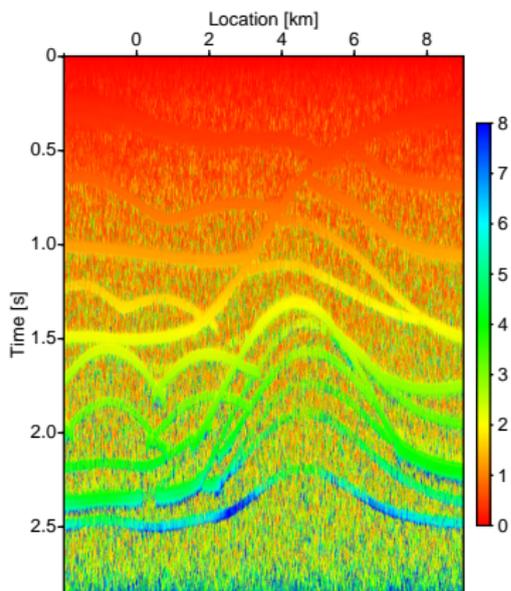
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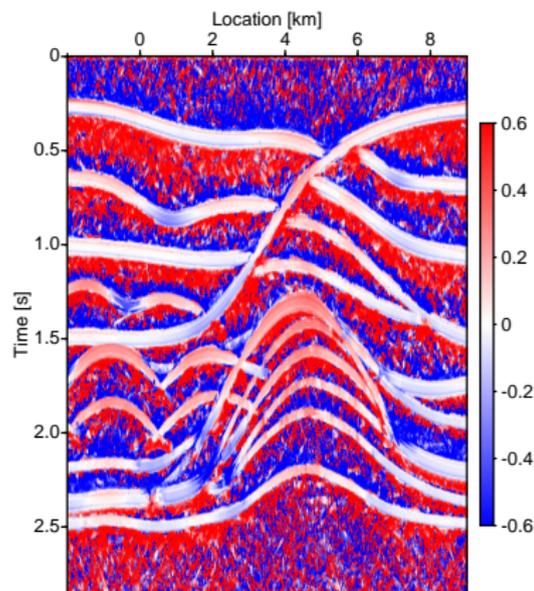
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1/Knip section [km]

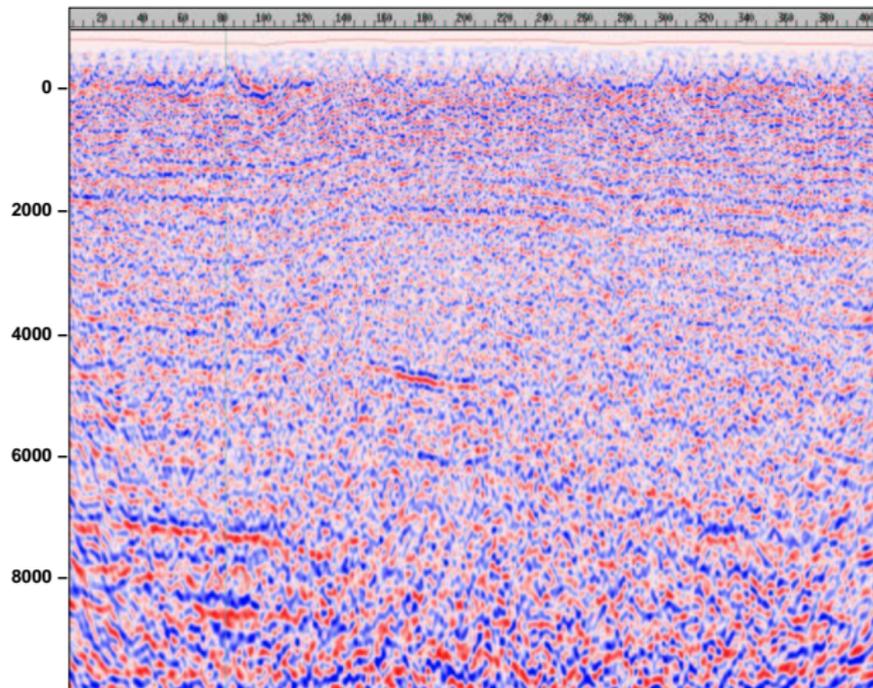


Kn section [1/km]

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Conventional 3D prestack depth migration
Data and image courtesy of ENI E&P division

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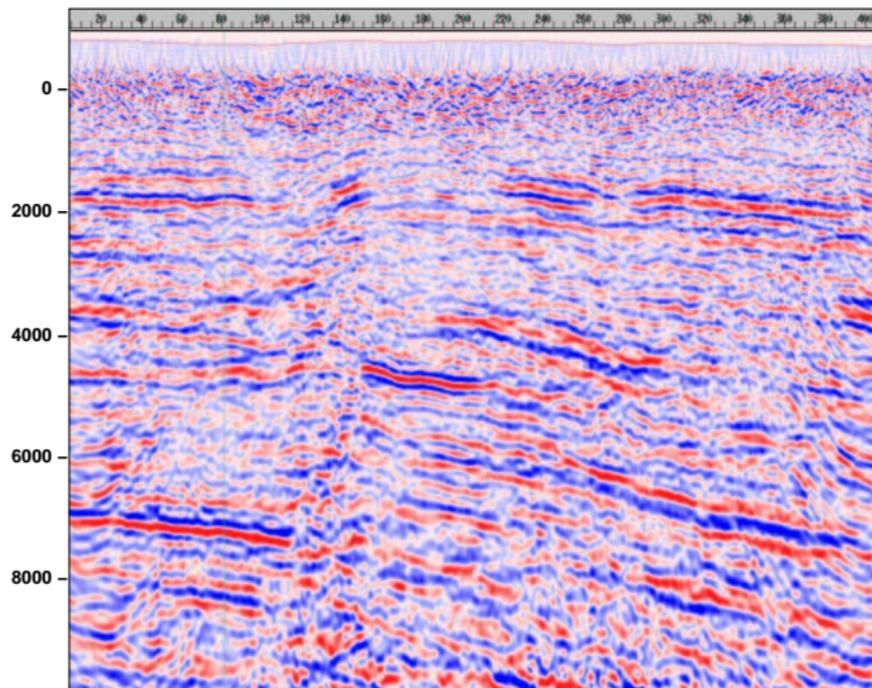
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3D poststack depth migration of CRS stack
Data and image courtesy of ENI E&P division

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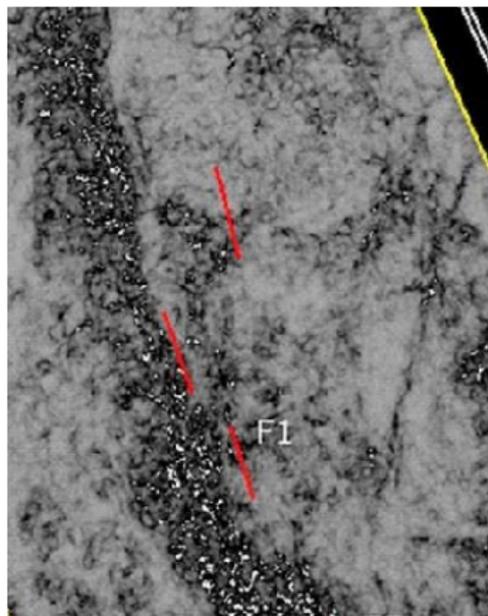
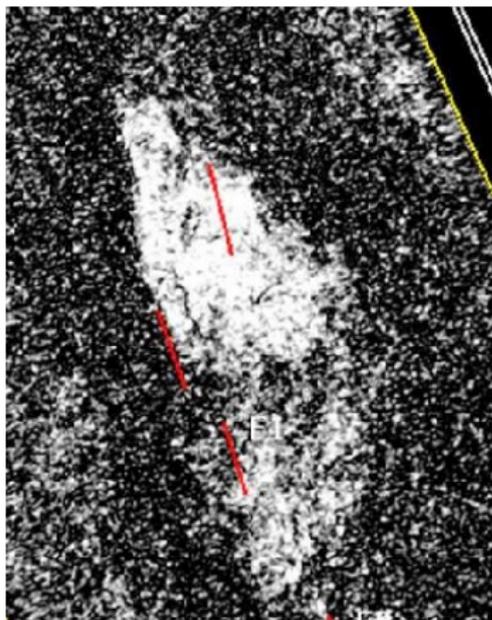
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Real data example

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Depth slices of coherence cubes, conventional vs. CRS
Data and image courtesy of ENI E&P division

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Further real data examples:

- ▶ *Seismic imaging practice with CRS stack*
Trappe et al., session S5B
- ▶ *Anwendung des Common-Reflection-Surface Stack auf reflexionsseismische Daten*
Chávez Zander et al., session S5C
- ▶ *A seismic reflection imaging workflow based on the CRS stack: a data example from the Oberrheingraben*
Hertweck et al., session S5D
- ▶ *Salt tectonics in the Southern Levantine Basin (GEMME I)*
Netzeband et al., session SMP11
- ▶ *CRS imaging of salt tectonic structures in the Southeastern Mediterranean Sea (GEMME I)*
Gradmann et al., session SMP12

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Results so far

- ▶ simulated zero-offset section with high signal/noise ratio
- ▶ 3 stacking parameters or *kinematic wavefield attributes* related to
 - ▶ first and second traveltimes derivatives
 - ▶ alternative interpretation: propagation direction and curvatures of wavefronts due to hypothetical experiments
- ▶ remaining tasks:

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Macrovelocity model determination

- ▶ pick local reflection events in simulated zero-offset section
- ▶ extract associated wavefield attributes
- ▶ define (simple) initial model of velocity distribution and reflector segments
- ▶ forward-modeling of traveltimes and wavefield attributes by dynamic ray tracing
- ▶ iterative minimization of misfit between forward-modeled and picked traveltimes and attributes
 - ↳ tomographic inversion approach, yields smooth velocity model consistent with picked data
 - ↳ data-driven basis for time-depth transformation

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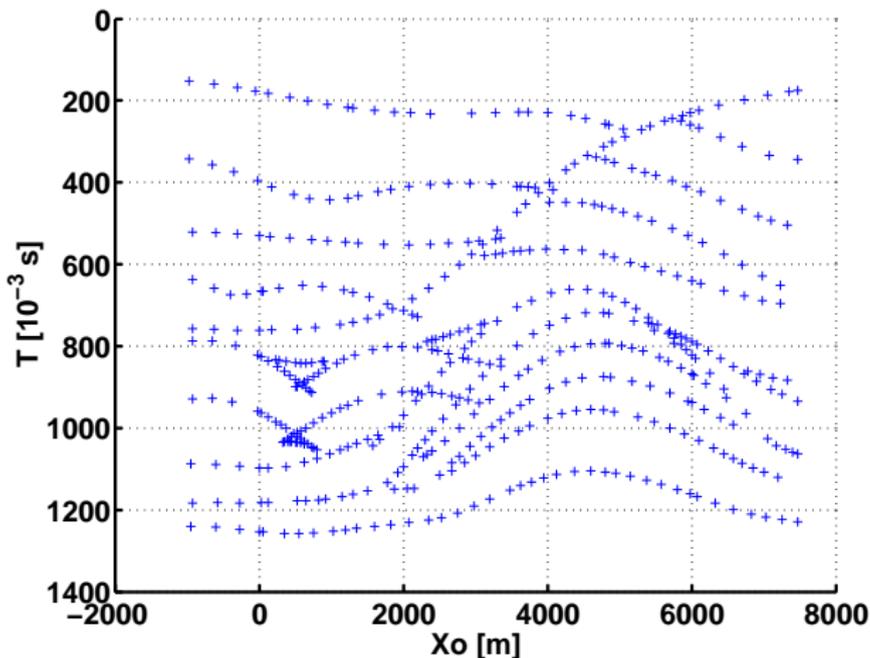
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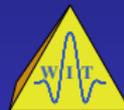
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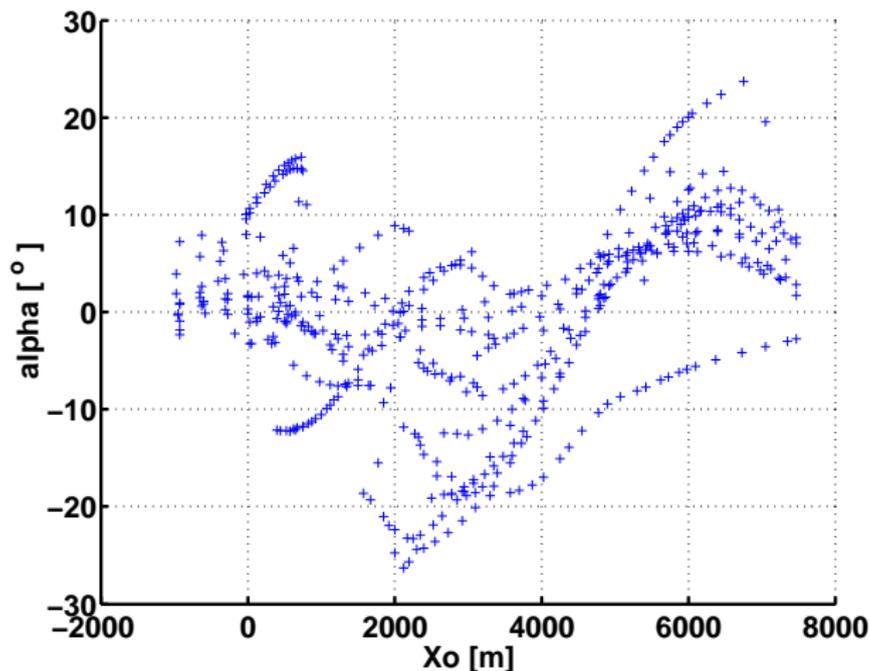
Picked zero-offset samples



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Extracted wavefield attributes (first order)

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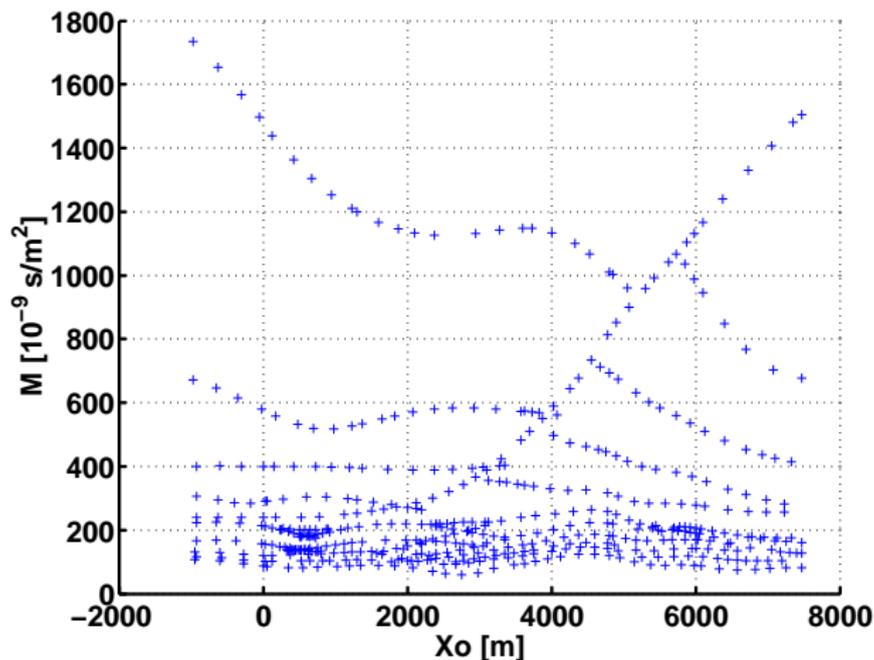
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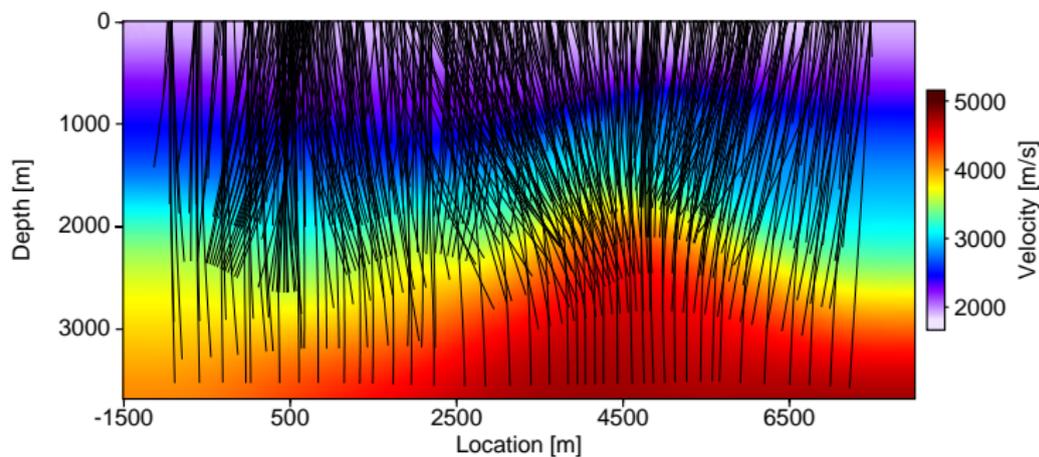
Extracted wavefield attributes (second order)



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Reconstructed velocity model and normal rays

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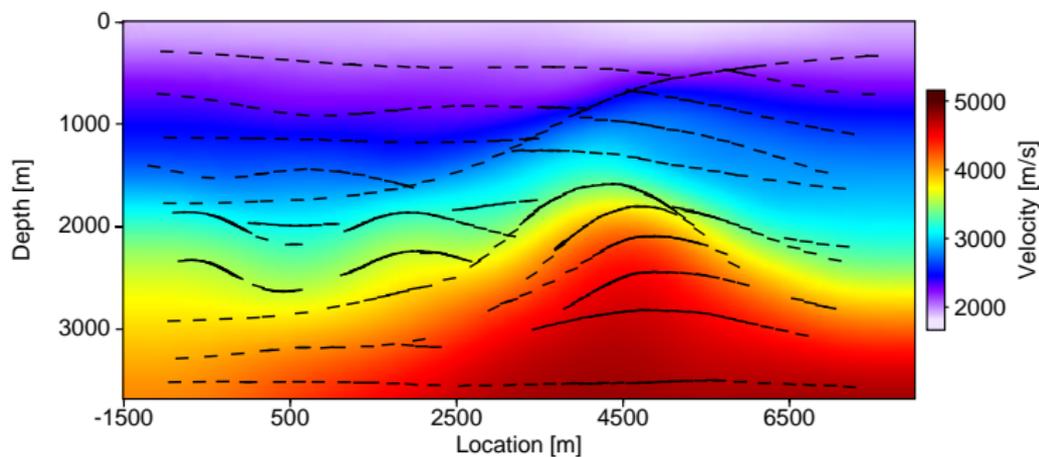
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Reconstructed velocity model and reflector segments

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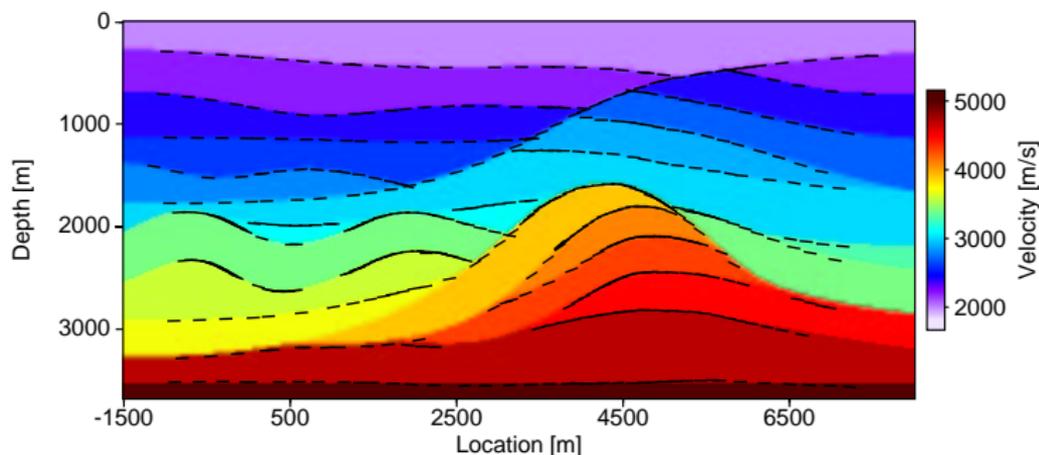
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Original velocity model overlain with
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Time-depth transformation

- ▶ macrovelocity model allows time-depth transformation:
 - ▶ poststack depth migration of CRS stack result and/or
 - ▶ prestack depth migration of entire multicoverage data
- ▶ results in structural image in depth domain
- ▶ prestack depth-migrated images suited to evaluate the macrovelocity model

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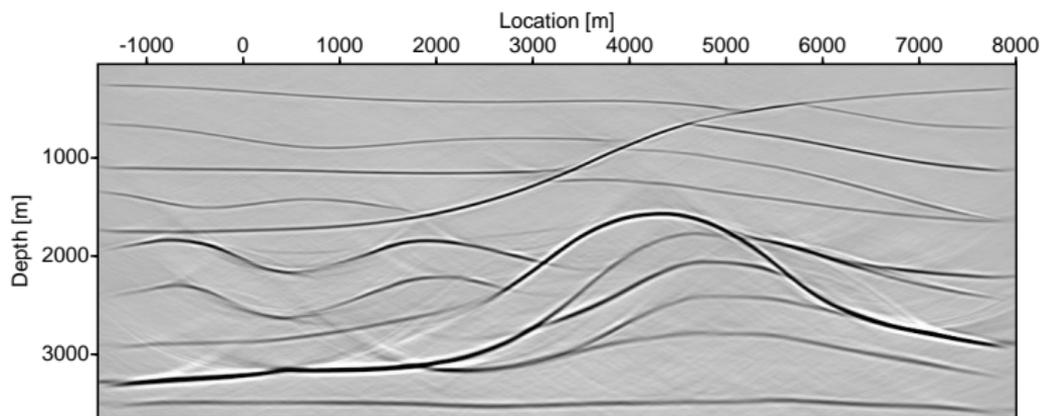
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Poststack migration of CRS stack section

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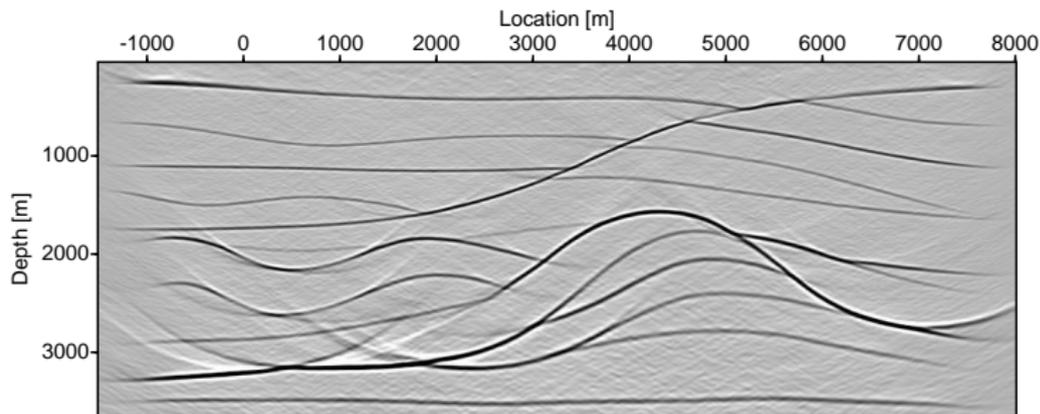
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Stack of migration results for different offsets

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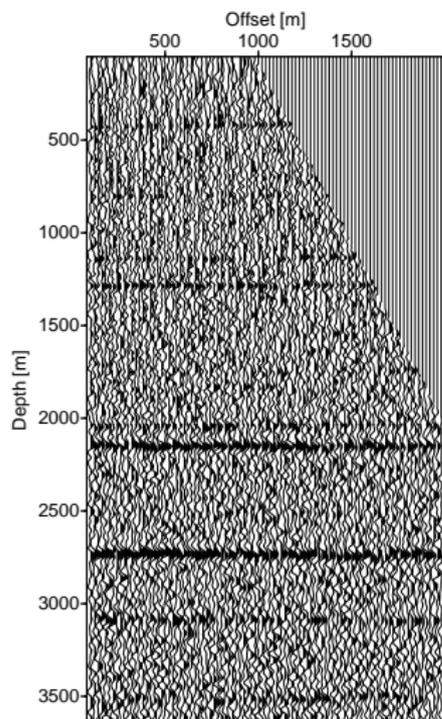
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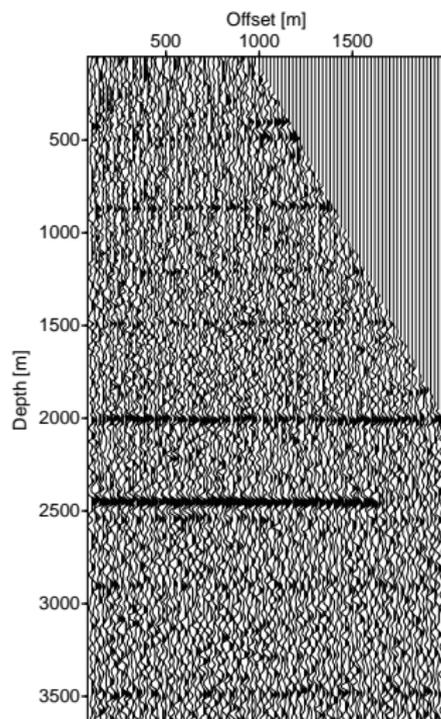
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Common-image gather $x=3000$ m



Common-image gather $x=6000$ m

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- ▶ consistent, entirely data-driven imaging approach
- ▶ largely automated approach
- ▶ also applicable for 3D data
- ▶ various extensions available:

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- ▶ various extensions available:

- ▶ acquisition surface with rugged topography
- ▶ simulation of arbitrary acquisition geometries

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 - ▶ residual static corrections
 - ▶ estimation of projected Fresnel zone and geometrical spreading factor
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I would like to thank

- ▶ my colleagues in Karlsruhe, especially
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 - ▶ Eric Duvencq (tomographic inversion)
 - ▶ Thomas Hertweck (migration)
- ▶ ENI E&P Division, Milano, Italy, for their data examples
- ▶ the sponsors of the Wave Inversion Technology (WIT) Consortium, Karlsruhe, Germany, for their support
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